## Stochastic Integration

Stochastic Integration

#### Remember...

If F is a continuously differentiable function with:

$$f(s) = \frac{dF(s)}{ds}$$

then:

$$\int_0^t X(s) dF(s) = \int_0^t X(s) f(s) ds$$

If F is not differentiable then we can still compute the integral but in Riemann(or Lebesgue)-Stieltjes sense:

$$\int_{0}^{t} X(s) dF(s) = \lim_{n \to \infty} \sum_{k=1}^{n} X(\frac{(k-1)t}{n}) (F(\frac{kt}{n}) - F(\frac{(k-1)t}{n}))$$

Stochastic Integration

ヘロト ヘアト ヘビト ヘビト

Э

We can't do the same thing if we want to replace F by W.

So we need to construct an integral in a different sense.

A priori is not clear that it can be done..

Idea:

- See if we can make sense of an integration for a small set of integrands.
- Try to reach more integrands by taking some limit.

A stochastic process  $\{X_t\}_{t \in [0, T]}$  is called simple if there exist real numbers:

$$0 = t_0 < t_1 < ... < t_p = T$$

and bounded random variables  $\Phi_i : \Omega \longrightarrow \mathbb{R}$  (i = 1, ..., p) with

 $\Phi_0 \quad \mathcal{F}_0$ -measurable and  $\Phi_i \quad \mathcal{F}_{t_i-1}$ -measurable

such that:

$$X_t(\omega)=\Phi_0(\omega)\mathbb{1}_0(t)+\sum_{i=1}^p\Phi_i(\omega)\mathbb{1}_{(t_{i-1},t_i]}(t)$$

for each  $\omega \in \Omega$ .

Stochastic Integration

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへの

In this case the integral can be defined in the usual way:

$$I_t(X) = \int_0^t X_s dW_s = \sum_{1 \le i \le k} \Phi_i (W_{t_i} - W_{t_{i-1}}) + \Phi_{k+1} (W_t - W_{t_k})$$

or, in a more compact notation:

$$I_t(X) = \sum_{1 \leq i \leq p} \Phi_i(W_{t_i \wedge t} - W_{t_{i-1} \wedge t})$$

where  $\wedge$  denotes the minimum of the two values.

Stochastic Integration

If X is a simple process:

•  $I_t(X)$  is a continuous martingale. In particular  $E(I_t(X)) = 0$  for all  $t \in [0, T]$ .

2 
$$E(I_t^2(X)) = E(\int_0^t X_s^2 ds).$$

Stochastic Integration

# Sketch of Proof: Part 1

We need to prove that:

$$E(I_t(X)|\mathcal{F}_s=I_s(X))$$

but

$$E(I_t(X)|\mathcal{F}_s = E(\sum_{1 \leq i \leq k} \Phi_i(W_{t_i} - W_{t_{i-1}}) + \Phi_{k+1}(W_t - W_{t_k})|\mathcal{F}_s)$$

Suppose that  $i_0$  is the index so that  $i_0 < s \le i_0 + 1$ .

Therefore we can separate the sums into two groups, the terms that involve things prior to s and the term that involve things after s.

The terms that involve things prior to s are all measurable w.r.t  $\mathcal{F}_s$  (and they amount to  $I_s(X)$ ) and for the terms that involve things after s:

$$E(\Phi_i(W_{t_i}-W_{t_{i-1}})|\mathcal{F}_s)=0$$
 ,  $t_{i-1}\geq s$ 

Why? We can prove it using iterated expectations.

Notice that  $\Phi_i$  is measurable wrt to  $\mathcal{F}_{t_{i-1}}$  so, it is known at time  $t_{i-1}$ . Therefore, whatever  $\Phi_i$  ends up being at time  $t_{i-1}$  it gets multiplied by a normal variable, so the expected value has to be zero.

Now, we have to deal with  $E(I_t(X)^2)$ 

Distributing the expression for the integral we get a bunch of terms like:

$$E(\Phi_i \Phi_j (W_{t_i} - W_{t_{i-1}}) (W_{t_j} - W_{t_{j-1}}))$$

Case  $i \neq j$ : If i > j then we can condition wrt  $\mathcal{F}_{i-1}$ :

$$E(E(\Phi_i \Phi_j (W_{t_i} - W_{t_{i-1}})(W_{t_j} - W_{t_{j-1}}))|\mathcal{F}_{i-1})$$

and observe that all the terms but the last one are measurables wrt  $\mathcal{F}_{i-1}$  (they are all known before that) so:

$$E(\Phi_i \Phi_j (W_{t_j} - W_{t_{j-1}}) E((W_{t_i} - W_{t_{i-1}}) | \mathcal{F}_{i-1})) = 0$$

(ロ) (同) (E) (E) (E) (O)(O)

Case i = j:

$$egin{aligned} & E(\Phi_i^2(W_{t_i}-W_{t_{i-1}})^2) = E(\Phi_i^2E((W_{t_i}-W_{t_{i-1}})^2|\mathcal{F}_{t_{i-1}})) \ & = E(\Phi_i^2(t_i-t_{i-1})) \end{aligned}$$

So, the cross terms vanish and the i = j terms are the only ones that survive, then:

$$E(I_t(X)^2) = E(\sum_{i=1}^k \Phi_i^2(t_i - t_{i-1})) = E(\int_0^t X_s^2 ds)$$

Stochastic Integration

# Measurability

A stochastic process  $X_t$  is **measurable** if the mapping:

 $[0,\infty)\longrightarrow \mathbb{R}^n$ 

$$(s,\omega) \longrightarrow X_s(\omega)$$

is measurable in the product space.

We will need a related (but different) notion: A stochastic process  $X_t$  is **progressively measurable** if, for every t, the mapping:

$$[0,t) \longrightarrow \mathbb{R}^n$$

$$(s,\omega) \longrightarrow X_s(\omega)$$

is measurable (w.r.t the information up to time t).

Stochastic Integration

Theorem: IF  $X_t$  is a progressively measurable process so that  $E(\int_0^T X_t^2 dt) < \infty$  then  $X_t$  can b approximated by simple processes  $X^{(n)}$  so that:

$$\lim_{n\to\infty} E(\int_0^T (X_s - X_s^{(n)})^2 ds = 0$$

Stochastic Integration

How do we define an integral for general integrands?

If we call  $L^2[0, T]$  the space of progressively measurable processes with  $E(\int_0^T X_t^2 dt) < \infty$  then there exists a unique mapping J from  $L^2[0, T]$  into the space of continuous martingales on [0, T] so that:

• IF X is a simple process then the mapping J coincides with the integral we defined before (with probability 1).

2 
$$E(J_t(X)^2) = E(\int_0^t X_s^2 ds).$$

This equality is called the Itô isometry.

We define J as the stochastic integral of X w.r.t. W and denote:

$$\int_0^t X_s dW_s = J_t(X)$$

### Itô Formula.

Suppose that  $W_t$  is a Brownian motion and  $X_t$ :

$$X_t = X_0 + \int_0^t K_s ds + \int_0^t H_s dW_s$$

Let  $f : \mathbb{R} \longrightarrow \mathbb{R}$  be twice continuously differentiable. Then:

$$f(X_t) = f(X_0) + \int_0^t f'(X_s) dX_s + \frac{1}{2} \int_0^t f''(X_s) H_s^2 ds$$
  
=  $f(X_0) + \int_0^t (f'(X_s) K_s + \frac{1}{2} \int_0^t f''(X_s) H_s^2) ds$   
+  $\int_0^t f'(X_s) H_s dW_s$ 

Let us consider a partition of [0, t]. By Taylor:

$$f(X_t) - f(X_0) = \sum_{k=1}^m (f(X_{t_k}) - f(X_{t_{k-1}}))$$

$$=\sum_{k=1}^m f'(X_{t_{k-1}})(X_{t_k}-X_{t_{k-1}})$$

$$+rac{1}{2}\sum_{k=1}^{m}f''(\eta_k)(X_{t_k}-X_{t_{k-1}})^2$$

where  $\eta_k(\omega)$  is an intermediate point.

Stochastic Integration

## Itô Formula. Idea of proof

$$\sum_{k=1}^{m} f'(X_{t_{k-1}})(X_{t_k} - X_{t_{k-1}}) = \sum_{k=1}^{m} f'(X_{t_{k-1}})(B_{t_k} - B_{t_{k-1}}) + \sum_{k=1}^{m} f'(X_{t_{k-1}})(M_{t_k} - M_{t_{k-1}})$$

where:

$$B_t = \int_0^t K_s ds$$
 and  $M_t = \int_0^t H_s dW_s$ 

Stochastic Integration

・ロ> <回> <三> <三> <三> <三> <三> <三> <三> <</li>

In regular calculus the term:

$$\frac{1}{2}\sum_{k=1}^m f''(\eta_k)(X_{t_k}-X_{t_{k-1}})^2$$

goes to zero as the norm of the partition goes to 0 since f'' is bounded (by Q) and then we can do:

$$\leq Q \|\Pi\| rac{1}{2} \sum_{k=1}^m (x_k - x_{k-1}) \longrightarrow 0$$

Stochastic Integration

But in this case that is not true. We can replace X by its two pieces again

$$\frac{1}{2}\sum_{k=1}^{m}f''(\eta_k)(X_{t_k}-X_{t_{k-1}})^2$$

$$=\frac{1}{2}\sum_{k=1}^{m}f''(\eta_k)(B_{t_k}+M_{t_k}-B_{t_{k-1}}-M_{t_{k-1}})^2$$

Developing the square we get 3 terms:

(B<sub>tk</sub> - B<sub>tk-1</sub>)<sup>2</sup>, which is a "calculus" term and so it goes to 0.
(B<sub>tk</sub> - B<sub>tk-1</sub>)(M<sub>tk</sub> - M<sub>tk-1</sub>), which can also be bounded using the norm of the partition.

( $M_{t_k} - M_{t_{k-1}}$ )<sup>2</sup>, which does not go to zero.

#### Proving that

$$\sum_{k=1}^m f''(\eta_k)(M_{t_k}-M_{t_{k-1}})^2 \longrightarrow \int_0^t f''(X_s)H_s^2ds$$

is somewhat technical but intuitively clear since

$$(M_{t_k} - M_{t_{k-1}})^2 \sim H(t_k)^2(t_k - t_{k-1})$$

Stochastic Integration