

From Random Variables to Random Processes

Random Processes

In probability theory we study spaces $(\Omega, \mathcal{F}, \mathcal{P})$ where Ω is the space, \mathcal{F} are all the sets to which we can measure its probability and \mathcal{P} is the probability.

Example: Toss a die twice.

$$\Omega = \{(1, 1), (1, 2), \dots, (6, 6)\}$$

\mathcal{F} = All the subsets of Ω .

\mathcal{P} assigns the number $\frac{1}{36}$ to each pair.

We can do things like computing the probability of getting a 1 in the first trial or computing the probability of the sum of the two being larger than 3.

Each possible result of the experiment is denoted with the letter ω .

Now, we can also define a function

$$X : \Omega \longrightarrow \mathbf{R}$$

For example X = "first coordinate" or X = "sum of the two numbers".

X induces a probability on the real line by doing:

$$P(A) = \mathcal{P}(X \in A)$$

P is what is usually called the distribution of X .

From X we can measure expected value ($E(X)$), variance ($\text{Var}(X)$), standard deviation, etc.

The numeric result of an experiment can be denoted by $X(\omega)$.

Now, suppose that you were to repeat the experiment every day. Instead of X we would have X_t or $X(t)$.

After 1 year of doing so we would have created a whole function. If we were to do it again we would obtain:

$$X(t, \omega_2)$$

$X(t)$ is a stochastic process.

The result of an experiment $X(t, \omega)$ is a "random function".

From this X we can measure the expected value at a given time

$$E(X(t_0))$$

the expected value of the difference at two different times

$$E(X(t_1) - X(t_0))$$

the variance at a given time

$$\text{Var}(X(t_0))$$

etc.

In many examples Ω is not explicitly known

What is Ω in finance?

Brownian Motion

$B(t)$ is a Brownian Motion if:

- 1) $B(t)$ is cont in t .
- 2) $B(t+h) - B(t) \sim N(0, \sqrt{h})$.
- 3) Indep. increments:

$B(t_n) - B(t_{n-1}), \dots, B(t_1) - B(t_0)$ are independent.

Notice that, in particular,

$$\text{Var}(B(t_j) - B(t_{j-1})) = t_j - t_{j-1}.$$

Brownian Motion

Now, consider an interval $I = [0, T]$ and consider a partition of I .

$$\Pi = t_0, t_1, \dots, t_n \text{ with } 0 = t_0 < t_1 < \dots < t_n = T$$

The mesh of the partition is defined as

$$\|\Pi\| = \max_j |t_j - t_{j-1}|$$

Given a function f we define the first variation and the quadratic variation as:

$$FV(f)(T) = \lim_{\|\Pi\| \rightarrow 0} \sum_{j=0}^{j=n} |f(t_j) - f(t_{j-1})|$$

$$\langle f \rangle (T) = \lim_{\|\Pi\| \rightarrow 0} \sum_{j=0}^{j=n} |f(t_j) - f(t_{j-1})|^2$$



Brownian Motion

If f is differentiable:

$$f(t_j) - f(t_{j-1}) = f'(t_j^*)(t_j - t_{j-1})$$

and therefore

$$FV(f)(T) = \int_0^T |f'(t)| dt$$

and

$$\langle f \rangle (T) = \lim_{\|\Pi\| \rightarrow 0} \sum_{j=0}^{j=n} |f'(t_j^*)|^2 (t_j - t_{j-1})^2$$

$$\leq \lim_{\|\Pi\| \rightarrow 0} \|\Pi\| \sum_{j=0}^{j=n} |f'(t_j^*)|^2 |(t_j - t_{j-1})| = 0$$

Fact:

$$\langle B \rangle (t) = T$$

(This would say, in particular, that $B(t)$ is not differentiable)

Define $D_k = B(t_{k+1}) - B(t_k)$

The quadratic variation is the limit of expressions like:

$$Q_{\Pi} = \sum_{k=0}^{n-1} D_k^2$$

We want to prove that

$$\lim_{\|\Pi\| \rightarrow 0} (Q_{\Pi} - T) = 0$$

Consider

$$Q_{\Pi} - T = \sum_{k=0}^{n-1} D_k^2 - (t_{k+1} - t_k)$$

It is easy to see that the expected value is 0.

Brownian Motion

Because of independent increments

$$\begin{aligned}\text{Var}(Q_{\Pi} - T) &= \sum_{k=0}^{n-1} \text{Var}(D_k^2 - (t_{k+1} - t_k)) = \sum_{k=0}^{n-1} \mathbb{E}(D_k^2 - (t_{k+1} - t_k))^2 \\ &= \sum_{k=0}^{n-1} \mathbb{E}(D_k^4 - 2D_k^2(t_{k+1} - t_k) + (t_{k+1} - t_k)^2) \\ &= \sum_{k=0}^{n-1} (3(t_{k+1} - t_k)^2 - 2(t_{k+1} - t_k)^2 + (t_{k+1} - t_k)^2) \\ &= \sum_{k=0}^{n-1} 2(t_{k+1} - t_k)^2 \leq 2\|\Pi\| T < \infty\end{aligned}$$

Which is what we wanted

Now, notice that

$$E((B(t_{k+1}) - B(t_k))^2 - (t_{k+1} - t_k)) = 0$$

$$\text{Var}((B(t_{k+1}) - B(t_k))^2 - (t_{k+1} - t_k)) = 2(t_{k+1} - t_k)^2$$

(To see this consider $X \sim N(0, \sigma)$.

Then $E((X^2 - \sigma^2)^2) = E(X^4) - \sigma^4$, but $E(X^4) = 3\sigma^4$

Or, which is the same:

$$E((B(t_{k+1}) - B(t_k))^2) = (t_{k+1} - t_k)$$

$$E(((B(t_{k+1}) - B(t_k))^2 - (t_{k+1} - t_k))^2) = 2(t_{k+1} - t_k)^2$$

(To see this consider $X \sim N(0, \sigma)$.

Then $E((X^2 - \sigma^2)^2) = E(X^4) - \sigma^4$, but $E(X^4) = 3\sigma^4$

Brownian Motion

Therefore, since $(t_{k+1} - t_k)^2$ is very small when $(t_{k+1} - t_k)$ is small :

$$(B(t_{k+1}) - B(t_k))^2 \sim (t_{k+1} - t_k)$$

In differential notation:

$$dB(t)dB(t) = dt$$

Remind: Riemann-Stieltjes

In calculus we study Riemann integrals:

$$\int_a^b f(x)dx = \lim \sum f(x_i)(x_i - x_{i-1})$$

where the x_i s form a partition of the interval $[a, b]$ and the limit is taken as the norm of the partition goes to zero.

In that sum $(x_i - x_{i-1})$ represent the weight (or measure) we give to the interval $[x_i, x_{i-1}]$.

There is a generalization of that concept called Riemann-Stieltjes integral in which the weight assigned to each interval is given by a transformation $g(x)$.

$$\int_a^b f(x)dg(x) = \lim \sum f(x_i)(g(x_i) - g(x_{i-1}))$$

Remind: Riemann-Stieltjes

For us to be able to do that $g(x)$ has to satisfy some conditions.

For example if g is an increasing function we can do it.

In that case g represents a "deformation" of the original homogeneous measure.

A general class of functions for which this can be done is formed by the functions that have finite first variation.

Back to Brownian Motion

Given a function f how do we compute $df(B(t))$?

In calculus we do

$$\frac{d}{dt}f(B(t)) = f'(B(t))B'(t)dt$$

In differential notation

$$df(B(t)) = f'(B(t))B'(t)dt = f'(B(t))dB(t)$$

But now $B(t)$ is not differentiable, in particular $B(t+h) - B(t)$ is "too big". However, we know that $(B(t+h) - B(t))^2 \sim h$ so we try adding an extra term to the Taylor expansion:

Brownian Motion

So, let us think about the chain rule in both cases:

Let us take a smooth function f which we are going to compose with:

- 1 a function g also smooth.
- 2 a brownain motion B .

$$f(g(t_k)) - f(g(t_{k-1})) = f'(\xi)(g(t_k) - g(t_{k-1}))$$

where ξ is between $g(t_k)$ and $g(t_{k-1})$. Let us now divide both sides by $(t_k - t_{k-1})$ and let t_k and t_{k-1} be very close to each other to obtain:

$$(f \circ g)'(t_k) = f'(g(t_k))g'(t_k)$$

Brownian Motion

If, instead of developing up to order 1 we had developed up to order 2:

$$f(g(t_k)) - f(g(t_{k-1})) = f'(g(t_{k-1}))(g(t_k) - g(t_{k-1})) \\ + \frac{1}{2} f''(\xi)(g(t_k) - g(t_{k-1}))^2$$

Again, dividing both sides by $(t_k - t_{k-1})$ and letting t_k and t_{k-1} we see that the second term vanishes (why?). So, the result is the same.

Brownian Motion

Now, what happens if instead of g we have B ?

Suppose that we stop at order 1:

$$f(B(t_k)) - f(B(t_{k-1})) = f'(\xi)(B(t_k) - B(t_{k-1}))$$

We can't divide by $(t_k - t_{k-1})$ as before ($\frac{B(t_k) - B(t_{k-1})}{(t_k - t_{k-1})}$ blows up in the limit).

If we try going up to order 2:

$$f(B(t_k)) - f(B(t_{k-1})) = f'(B(t_{k-1}))(B(t_k) - B(t_{k-1})) \\ + \frac{1}{2}f''(\xi)(B(t_k) - B(t_{k-1}))^2$$

We still can't divide. But, what we can do is to make t_k and t_{k+1} be very close, sum over all the t'_k 's and see if the two terms on the right make sense. It turns out that this can be done (we will do this soon).

So, in the end:

$$\begin{aligned}df(B(t)) &= f'(B(t))dB(t) + \frac{1}{2}f''(B(t))(dB(t))^2 \\ &= f'(B(t))dB(t) + \frac{1}{2}f''(B(t))dt\end{aligned}$$

In integral form

$$\begin{aligned}f(B(T)) - f(B(0)) &= \int_0^T f'(B(t))dB(t) \\ &\quad + \frac{1}{2} \int_0^T f''(B(t))dt\end{aligned}$$

Example: $f(x) = \frac{1}{2}x^2$

$$f'(x) = x, f''(x) = 1$$

$$\frac{B^2(T)}{2} = \int_0^T B(t)dB(t) + \frac{1}{2}T$$

We should compare this to

$$\int_0^T xdx = \frac{T^2}{2}$$

...so, in stochastic calculus, we have an extra term

Remark:

When one defines the stochastic integral one finds that

$$E\left(\int_0^T B(s)dB(s)\right) = 0$$

On the other hand we know that $E\left(\frac{B^2(T)}{2}\right) = \frac{T}{2}$.

So...if we did not have the extra term we would be in trouble.

Let us assume that the return of stocks is governed by:

$$\frac{S_{t+1} - S_t}{S_t} = \mu t + \phi \text{ where } \phi \sim N(0, \sigma)$$

In continuous time:

$$\frac{dS}{S} = \mu dt + \sigma dB.$$

How do I solve that? (how do I find S_t ?)

If we were talking regular calculus the solution would be $\log(S)$.
So, let's try the same solution:
Using Taylor:

$$\log(S_t) = \log(S_0) + \frac{1}{S_0}dS_0 - \frac{1}{2} \frac{1}{S_0^2}(dS_0)^2$$

I can replace $dS_0 = S_0\mu dt + S_0\sigma dB$.

$$\text{Also, } (dS_0)^2 = S_0^2\mu^2 dt^2 + S_0^2\sigma^2 dB^2 + 2\mu\sigma S_0^2 dt dB$$

However, I know that $dB^2 \sim dt$.

So, the term containing dB^2 is the biggest of them three.

If I now discard all the terms smaller than dt we end up with:

$$\log(S_t) = \log(S_0) + \frac{1}{S_0}(S_0\mu dt + S_0\sigma dB) - \frac{1}{2}S_0^2\sigma^2 dt$$

or

$$\log(S_t) = \log(S_0) + (\mu dt + \sigma dB) - \frac{1}{2}\sigma^2 dt$$

$$S_t = S_0 e^{(\mu - \frac{1}{2}\sigma^2)t + \sigma B(t)}$$

In general, from time t to time $t + h$ the solution evolves as:

$$S_{t+h} = S_t e^{(\mu - \frac{1}{2}\sigma^2)h + \sigma(B(t+h) - B(t))}$$

But we know that $B(t + h) - B(t) \sim N(0, \sqrt{h})$. The we can rewrite as:

$$S_{t+h} = S_t e^{(\mu - \frac{1}{2}\sigma^2)h + \sigma\sqrt{h}X} \text{ where } X \sim N(0, 1)$$